#### **CAP6671 Intelligent Systems**

Lecture 1: Introduction

Instructor: Dr. Gita Sukthankar Email: gitars@eecs.ucf.edu Schedule: T & Th 9:00-10:15am Location: HEC 302 Office Hours (in HEC 232): T & Th 10:30am-12

# Outline

- Course overview
- What are intelligent systems?
- Course requirements
- Web site:
  - http://www.eecs.ucf.edu/~gitars/cap6671/
- Reading: Katia Sycara, <u>Multiagent Systems</u>, AI Magazine 19(2): Summer 1998, 79-92. (posted on web site)

### **Course History**

- Course is being redesigned this semester and will be available on FEEDS next year
- Your feedback is important and welcome
- Derived from my 2 favorite courses at CMU
  - Planning, Execution, and Learning (R. Simmons)
  - Autonomous Multi-agent/Multi-robot Systems (T. Balch)
- Course objectives:
  - Learn how to build an intelligent agent system
  - Tackle some of the AI challenge problems
  - General exposure to the literature on intelligent systems

### Introductions

- Introduce yourself:
  - Your name
  - Masters or Ph.D/how many years at UCF?
  - What did you do before coming to UCF?
  - Which faculty member(s) do you work with?

• What is an intelligent system?

What are some examples of intelligent systems?

What are the desiderata of an intelligent systems?

How do robotic systems differ from other types of intelligent systems?

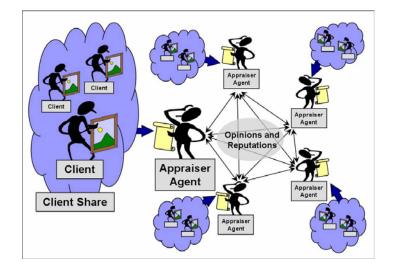
 How does the study of intelligent systems differ from the study of artificial intelligence as a whole?

Does artificial intelligence have to mimic human intelligence?

### Course Outline

- Algorithms for creating intelligent behavior
  - Planning: HTN planning, MDP planning
  - Learning: Reinforcement learning
  - Coordination mechanisms: team planning, auctionbased mechanisms
- Robotic agents
- Architecting intelligence (sense, think, act in real-time):
  - 3-tier architectures
  - Cognitive architectures

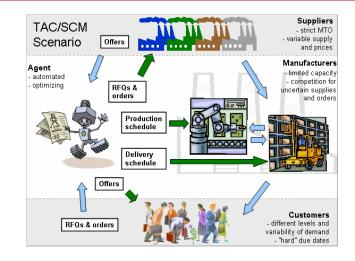
### AI Challenge Problems



#### Agent Reputation and Trust



Urban Rescue robot teams CAP6671: Dr. Gita Sukthankar



#### **Trading Agent Competition**



Robocup soccer

## Evaluation

- Homework (mainly implementation):
  - Planning
  - Learning
  - Coordination
- Lead one class discussion
- Midterm exam covering the reading
- Final project: AI challenge problem