### 3D User Interface Travel Techniques

Lecture #9: Navigation I – Travel
Spring 2013
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#### **Universal 3D Interaction Tasks**

- Navigation
  - Travel motor component
  - Wayfinding cognitive component
- Selection
- Manipulation
- System control
- Symbolic input

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#### Travel

- The motor component of navigation
- Movement between 2 locations, setting the position (and orientation) of the user's viewpoint
- The most basic and common VE interaction technique, used in almost any large-scale VE

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#### **Travel Tasks**

- Exploration
  - travel which has no specific target
  - build knowledge of environment
- Search
  - naïve: travel to find a target whose position is not known
  - primed: travel to a target whose position is known
  - build layout knowledge; move to task location
- Maneuvering
  - travel to position viewpoint for task
  - short, precise movements

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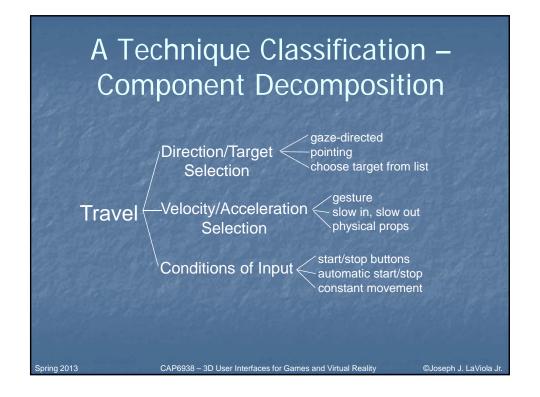
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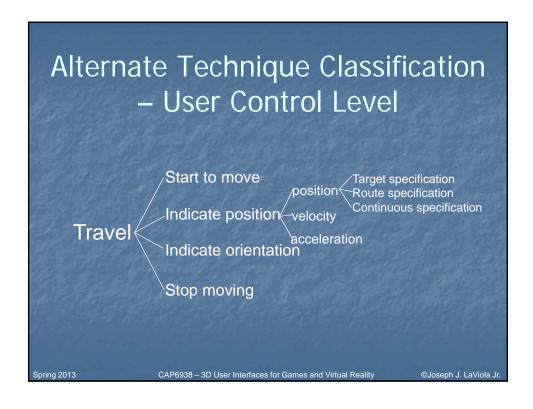
#### **Travel Characteristics**

- Travel distance
- Amount of curvature/number of turns in path
- Target visibility
- DOF required
- Accuracy required
- Other tasks during travel
- Active vs. passive
- Physical vs. virtual

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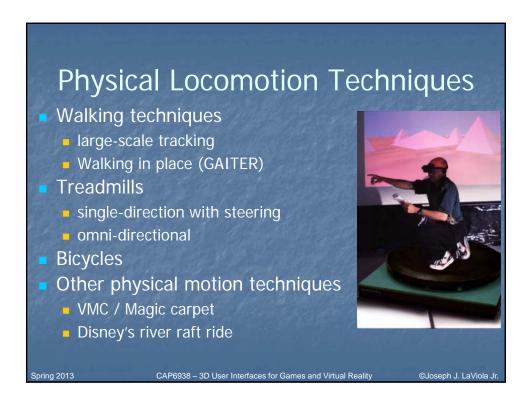


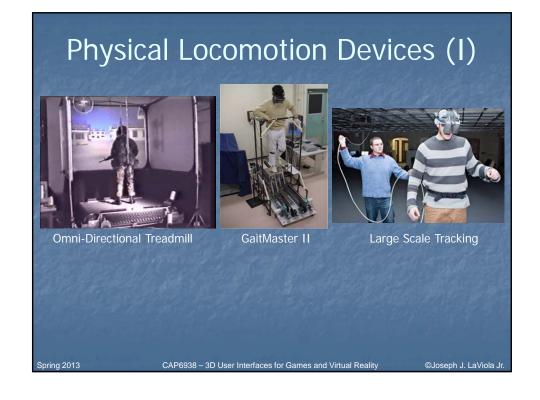
#### Travel Techniques

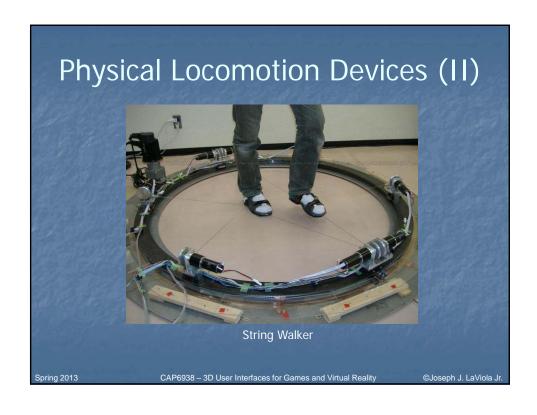
- Physical locomotion ("natural" metaphors)
- Steering techniques
- Route planning
- Target-based techniques
- Manual manipulation
- Viewpoint orientation techniques

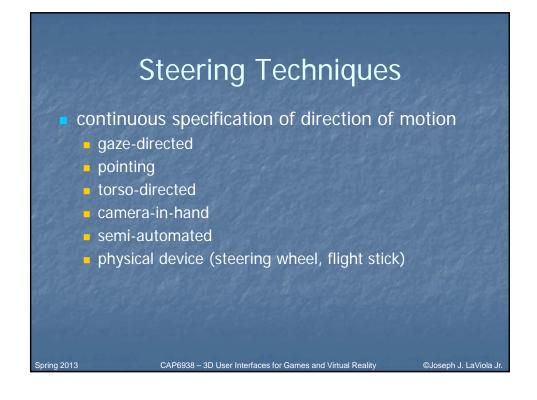
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#### Steering - Gaze-Directed

- Move viewpoint in direction of "gaze"
- Gaze direction determined from head tracker
- Cognitively simple
- Doesn't allow user to look to the side while traveling

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# Steering – Gaze-Directed Implementation

- Each frame while moving:
  - Get head tracker information
  - Transform vector [0,0,-1] in head CS to V=[x,y,z] in world CS
  - Normalize v:  $\hat{v} = \frac{v}{\|v\|}$
  - Translate viewpoint by  $(\hat{v}_x, \hat{v}_y, \hat{v}_z) \times current \_velocity$

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#### Pointing Technique

- Also a steering technique
- Use hand tracker instead of head tracker
- Slightly more complex, cognitively
- Allows travel and gaze in different directions – good for relative motion

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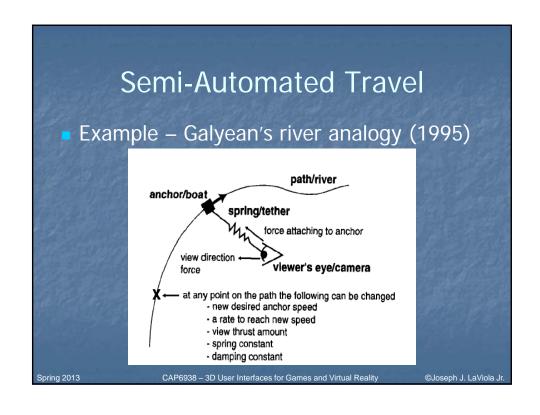
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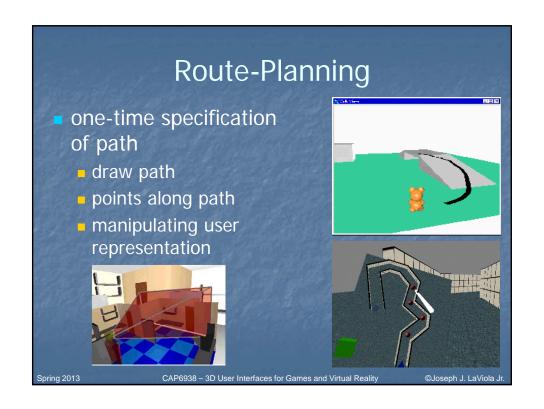
#### Pointing Implementation

- Each frame while moving:
  - Get hand tracker information
  - Transform vector [0,0,-1] in hand CS to *v*=[x,y,z] in world CS
  - Normalize v:  $\hat{v} = \frac{v}{\|v\|}$
  - Translate viewpoint by  $(\hat{v}_x, \hat{v}_y, \hat{v}_z) \times current \_velocity$

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### Target-Based Techniques

- discrete specification of goal
  - point at object
  - choose from list
  - enter coordinates
- Map/WIM-based target specification

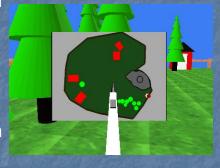
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### Map-Based Travel Technique

- User represented by icon on 2D map
- Drag icon with stylus to new location on map
- When released, viewpoint animated smoothly to new location



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#### Map-based Travel Implementation

- Must know
  - map scale relative to world: s
  - location of world origin in map CS:  $o=(x_o, y_o, z_o)$
- On button press:
  - if stylus intersects user icon, then each frame:
    - get stylus position in map CS: (x, y, z)
    - move icon to (x, 0, z) in map CS

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## Map-Based Travel Implementation (cont.)

- On button release:
  - Get stylus position in map CS: (x, y, z)
  - Move icon to (x, 0, z) in map CS
  - Desired viewpoint:  $p_{\nu} = (x_{\nu \nu}, y_{\nu \nu}, z_{\nu})$  where
    - $X_V = (X X_O)/S$
    - $Z_{\nu} = (Z Z_{0})/S$
    - $y_v = desired height at (x_v, y_v)$
  - Move vector:  $m = (x_v x_{curr}, y_v y_{curr}, z_v z_{curr}) * (velocity/distance)$
  - Each frame for (distance/velocity) frames: translate viewpoint by m

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## Manual Manipulation – Grabbing the Air Technique

- Use hand gestures to move yourself through the world
- Metaphor of pulling a rope
- Often a 2-handed technique
- May be implemented using Pinch Gloves™

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# Grabbing The Air Implementation (one-handed)

- On pinch:
  - Obtain initial hand position in world CS:  $(x_h, y_h, z_h)$
- Each frame until release:
  - Obtain current hand position in world CS:  $(x'_{h'}, y'_{h'}, z'_{h})$
  - Hand motion vector:  $m = ((x'_{h'}, y'_{h'}, z'_h) (x_{h'}, y_{h'}, z_h))$
  - Translate world by *m* (or viewpoint by *-m*)
  - $(x_{h'}, y_{h'}, z_h) = (x'_{h'}, y'_{h'}, z'_h)$
- Cannot simply attach objects to hand do not want to match hand rotations

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## Viewpoint Orientation Techniques

- Head tracking
- Orbital viewing
- Non-isomorphic rotation
- Virtual sphere

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#### **Next Class**

- Travel Wayfinding
- Readings
  - 3DUI Book Chapter 6

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